

D3250

AUTOMATIC BARRIER



OM MANUAL



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This equipment is part of a large range of traffic flow products. They are designed to be easy to install, as all settings and internal wiring have been completed in our factory. Any of the instructions in this manual should only be carried out by a qualified service engineer or a competent person.

The barriers are ready to bolt down, connect to a single phase power supply and have any pre-cut loops wired into them (Please note that loop detectors are sold separately). The steps must be completed before the power is turned on to prevent accidents.

The following information is a guide only, and whilst we have made every effort to be accurate and correct there may be printing errors which we cannot be held responsible for.

With a correct installation you can expect to enjoy many years of reliable service from this product, we do however recommend that the product has a bi-annual service carried out by a qualified engineer. Please contact our sales department should you need any advice on a recommended installer to be used for this.

Important Safety Notice



Automatic barriers are designed to Control the flow of vehicular traffic only. It can be dangerous to allow the passage of pedestrians and any other self-powered animal or device to utilise this method of access without appropriate warnings and or signage.

It may be necessary for the end user of this product to provide an alternative, safe method of access to cater for the previously mentioned categories.

The end user should fit all necessary signage and warning notices to either side of the gate, which should be visible and clear from all directions of approach.

The product that was shipped to you was designed with a control program to protect all categories from harm or affect this however is only a safety precaution and should not be modified or tampered with by any unauthorised person not sanctioned by the manufacturer.

Please sign and date below to say that you have read and understood this notice before ANY installation work:

/ /20

Information on using this manual



- ✍ Read all information thoroughly
- ✍ Pay attention to all safety advice
- ✍ Be aware of the symbols (shown above right and above left) as they have different meanings. One is an information symbol, the other a warning.
- ✍ There are many artists impressions of the product in this manual you should refer to the images as a guide only. Professional CAD drawings should be used as a reference drawing and nothing else. As before every effort has been made to be 100% accurate in this manual but we cannot make any guarantees.
- ✍ As we constantly innovate our products we may change the quoted spec and any other details that have been documented in this manual so you should always refer to the supplier to see if the manual that was shipped with your product is the latest edition.
- ✍ As with all electrical installations you should use a qualified electrician and obey all of the latest laws and regulations.
- ✍ Be sure to fill out and complete ALL paperwork where instructed as this manual is the equipments log book and maintenance manual.

The "Warnings" leaflet and "Instruction booklet" supplied with this product should be read carefully as they provide important information about safety, installation, use and maintenance.

Scrap packing materials (plastic, cardboard, polystyrene etc) according to the provisions set out by current standards. Keep nylon or polystyrene bags out of children's reach.

Keep the instructions together with the technical brochure for future reference.

This product was exclusively designed and manufactured for the use specified in the present documentation. Any other use not specified in this documentation could damage the product and be dangerous.

The Company declines all responsibility for any consequences resulting from improper use of the product, or use which is different from that expected and specified in the present documentation.

Do not install the product in explosive atmosphere.

The construction components of this product must comply with all applicable regulation. As for all non-EEC countries, the abovementioned standards as well as the current national standards should

be respected in order to achieve a good safety level.

The Company declines all responsibility for any consequences resulting from failure to observe Good Technical Practice when constructing closing structures (door, gates etc.), as well as from any deformation which might occur during use.

The installation must comply with the provisions set out by the applicable regulations.

Disconnect the electrical power supply before carrying out any work on the installation. Also disconnect any buffer batteries, if fitted.

Fit an omnipolar or magnetothermal switch on the mains power supply, having a contact opening distance equal to or greater than 3mm.

Check that a differential switch with a 0.03A threshold is fitted just before the power supply mains.

Check that earthing is carried out correctly: connect all metal parts for closure (doors, gates etc.) and all system components provided with an earth terminal.

Fit all the safety devices (photocells, electric edges etc.) which are needed to protect the area from any danger caused by squashing, conveying and shearing, according to and in compliance with the applicable directives and technical standards.

This article describes how your equipment will be delivered to you, specifications on the transportation used and advice including health & safety on movement of the equipment.



The manufacturer will use a qualified transport company to deliver the product conforming to the necessary regulations as detailed below:

- ✘ All drivers are qualified
- ✘ All drivers are tested once yearly (If applicable)
- ✘ All drivers carry risk assessments and method statements (available on request)
- ✘ They are controlled under law to conform as there are no trade regulation standards to comply with

Health and safety Considerations:

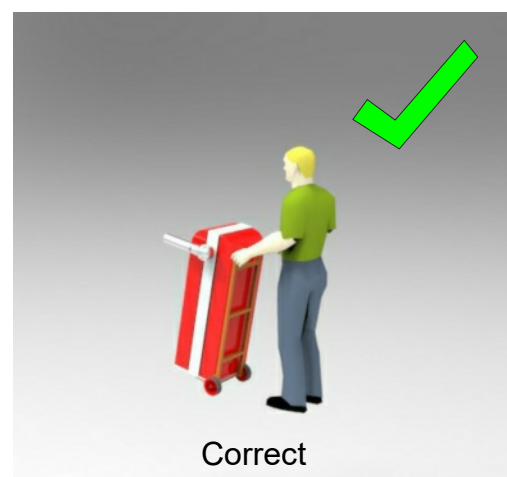
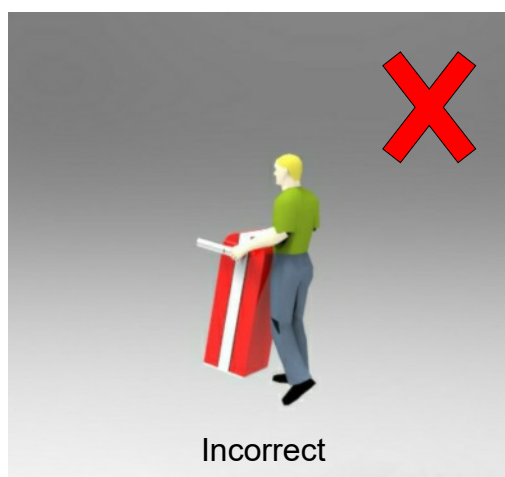
Moving Goods Safely (MGS) is a national project involving both the Health and Safety Executive (HSE) and Local Authorities (LA) working in partnership. The project aims to reduce injuries and ill-health arising from the movement of goods from supplier through haulier to the recipient and end user including any home deliveries. The project will focus upon the delivery and collection of goods and the hazards this generates. It covers the main areas that cause the majority of injuries and ill-health to workers, including:

- ✘ Workplace transport;
- ✘ Slips & trips, and;
- ✘ Musculoskeletal disorders (MSD).

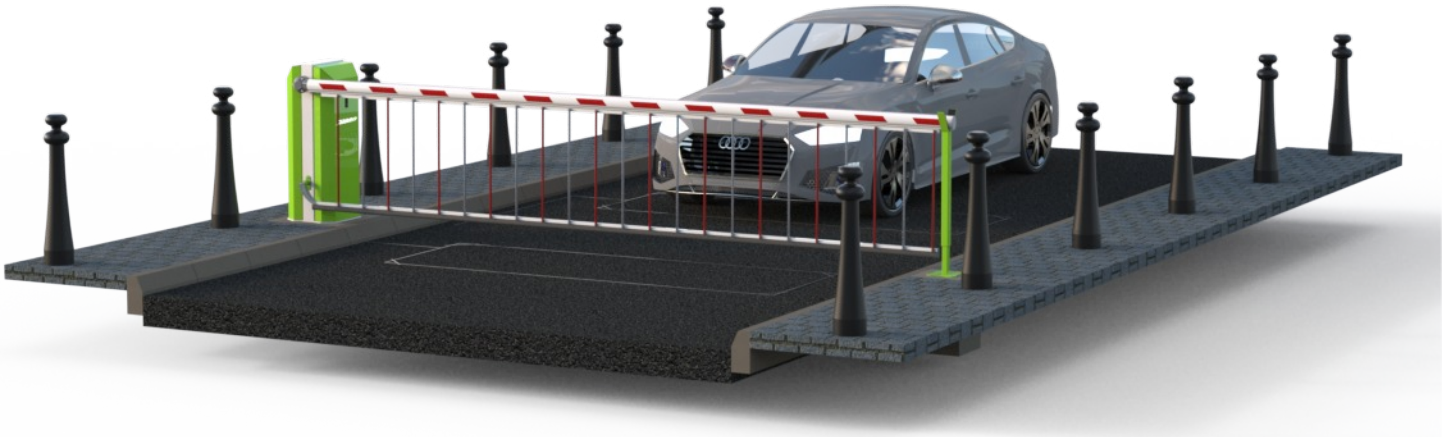
The movement of goods presents us, as health and safety regulators, with the challenge of dealing with a huge variety of issues. The commercial organisations involved within the movement of goods are diverse including haulier, third party logistics providers, pallet networks, retailers etc, with some very large companies, thousands of small businesses and the self-employed. The movement of goods is more than just trucks on the road with a large proportion of accidents happening at the delivery/collection sites that are often not directly under the control of the company making the delivery or collection. Communication and cooperation problems can arise due to the many organizations involved in the movement of the goods, and this can also lead to difficulties in effectively managing health and safety.

(Source H&S Executive UK 2008)

The barrier should ALWAYS! be moved with care and attention. The products are very heavy individually as well as a whole. You should not attempt to move this or any other products by unapproved handling methods.



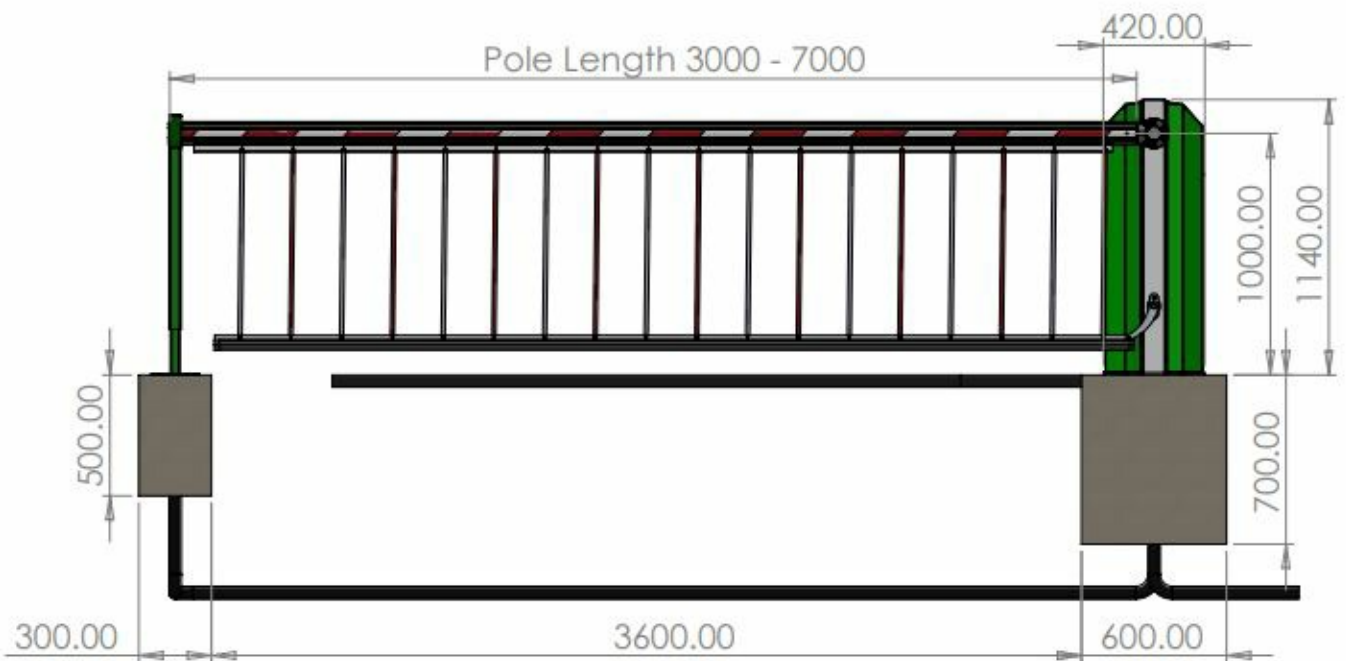
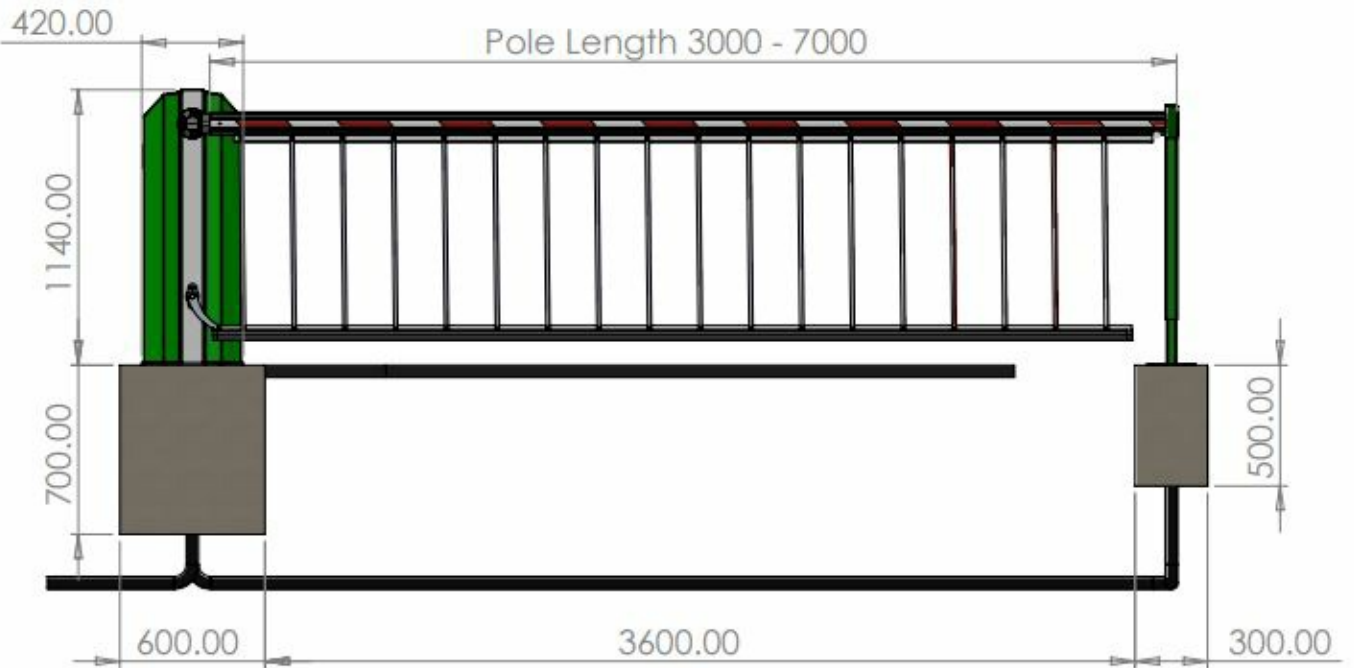
Shown below is a typical installation of a D3250 Automatic barrier for a single entrance. Control setup - A D3250 is a traffic barrier designed for easy access solutions requiring a reliable and simple yet affective way of segregating vehicles or managing traffic flow. With a variety of accessories to suit your individual; needs and specific site requirements.



Shown above is one of our D3250 barriers with a fixed bottom skirt. These can be fitted with a safety edge if required for extra protection to users and general public. The barrier comes with a few options for accessory poles such as a standard pole, an articulated arm for restricted heights such as underground car parks and a hi-bar skirt for complete coverage



Detailed below is the general layout and dimensions for a typical D3250 showing base size and depth, pole size and tip base.



General Barrier Products

On a typical delivery you will receive your D3250 barrier with a tip support, pole and a box of fixings as described below



Box of fixings

Your basic box of fixings will include;

- 4 x m16 x 125mm Anchor bolts
- 4 x m16 caps
- 4 x m12 x 125mm Anchor bolts
- 4 x m12 caps
- 2 x m6 x 80mm cap head bolts
- 6 x m6 washers
- 2 x m6 nylocks
- 2 x m6 x 20mm button head bolts
- 1 x Manual winder
- 2 x keys
- 1 x O & M manual



Step 1;

You Must first remove the D3250 barrier outer covers, Using the provided keys unlock the locks (Fig 1) and press the lock part to unlatch the lock and remove covers (Fig 2) please place these safely to prevent damage.

Fig 1



Fig 2



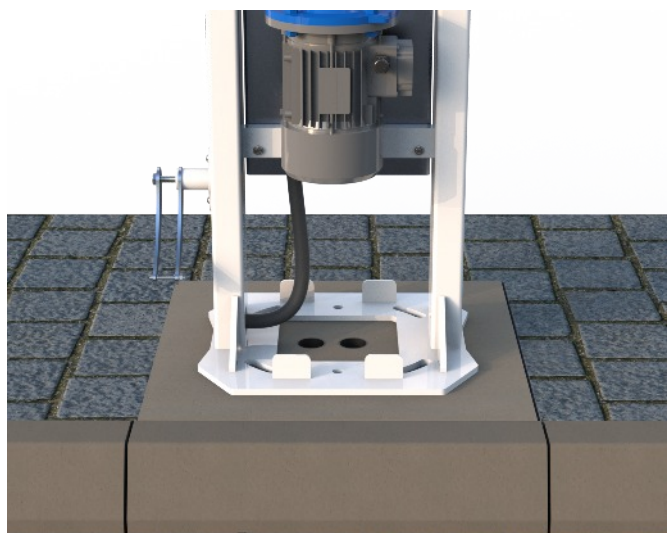
Step 2;

Lower your D3250 barrier onto the prepared foundations and locate centrally (see fig 3) Be aware of your ducting whilst lowering the barrier into place so that you have ease of access for your mains and trigger cables etc.(Fig 4)

Fig 3



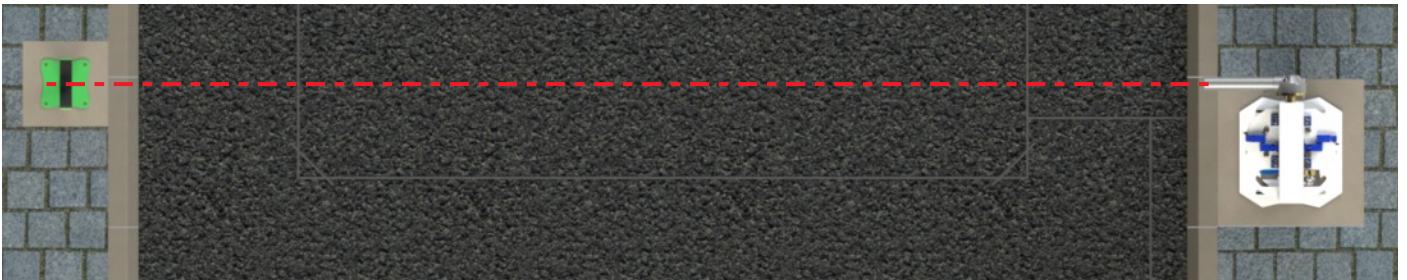
Fig 4



Step 3;

Align your barrier with your tip support using a string line or similar product to ensure correct alignment of barrier/ pole and tip support. (Fig 5)

Fig 5

**Step 4;**

Drill each hole for the barrier central in each slot using a 16mm sds bit and suitable drill, This is to allow full use of the slotted holes should you need a slight adjustment when required. (Fig 6)

When drilled, knock the m16 anchor bolts into place using a suitable lump or copper hammer and tighten using a 24mm spanner or socket. These should be tightened to 115nm of torque for suitable strength. (Fig 7)

Fig 6

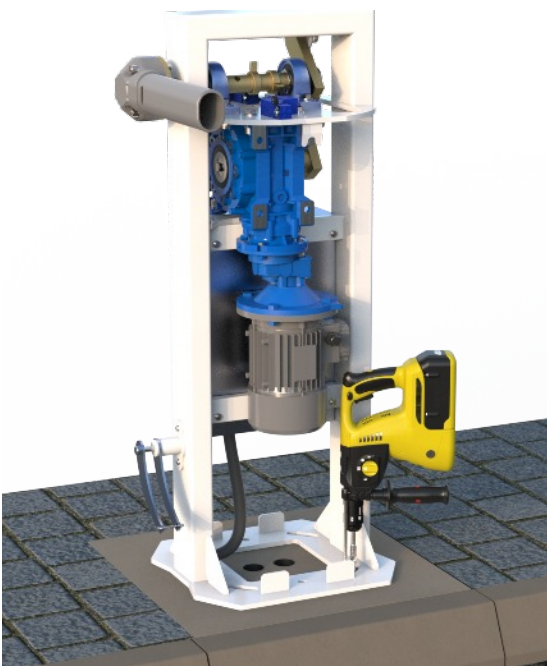
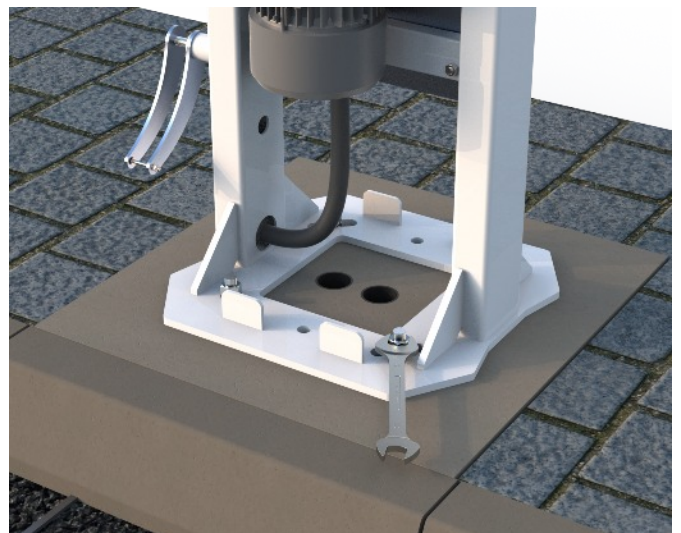


Fig 7



Step 5;

Now that the barrier is bolted you can (using suitable packers) level the product off ensuring the barrier is true and level. (Fig 8) If the barrier needs more than 10mm of packing be sure to grout up with concrete to ensure a stable and neat job.

**Step 6;**

Adding the pole: Now that your barrier is installed and level, with extreme care the pole can be unwrapped and fitted to the pole arm adapter (fig 9) and fixing using the M6 x x80mm cap head bolts (fig 10)

Fig 9

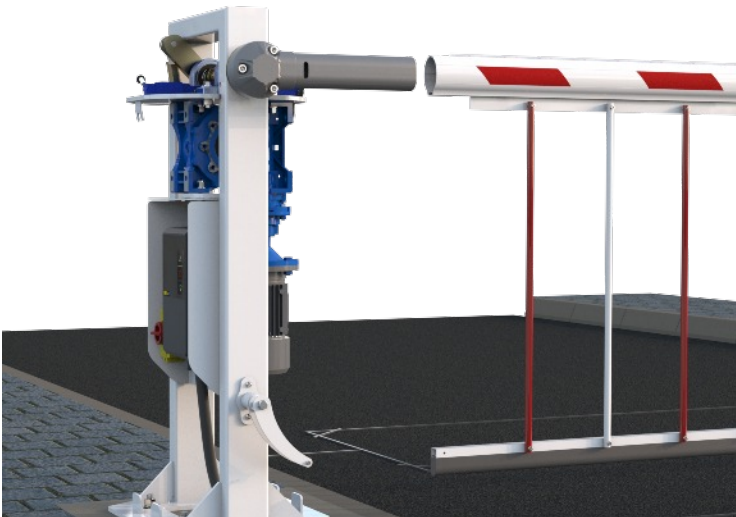
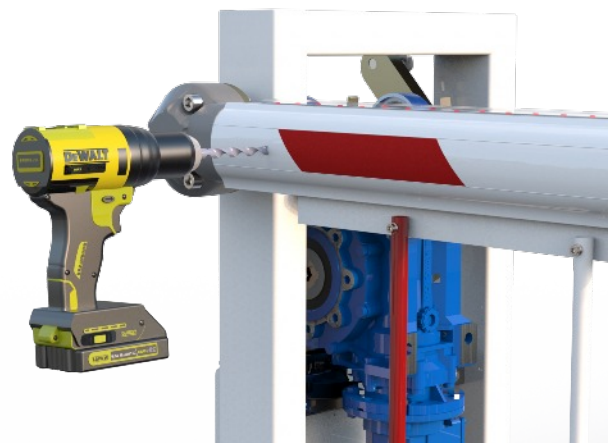


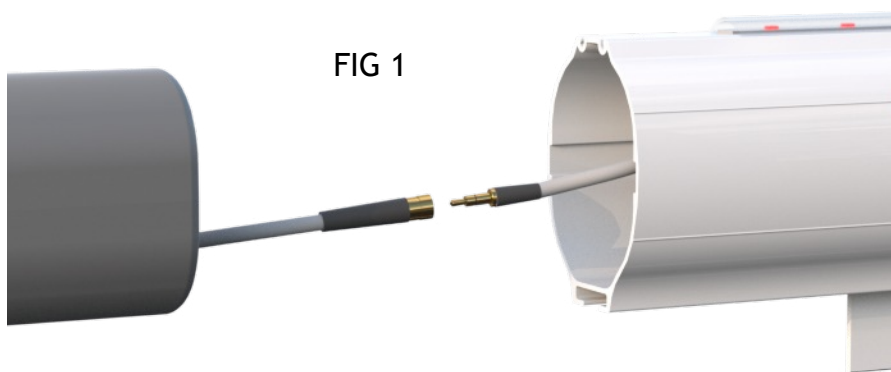
Fig 10



Note, If the pole has LED Lights or a safety edge, this MUST be connected at this point. The LED lights require simply plugging in, the safety edge will need joining. For this we would always recommend the use of gel crimps or other suitable water resistant connectors.

When connecting the pole to the barrier you may have up to three options for different types of connections depending on what's been ordered with your pole. Shown below are the examples of this and a brief guide and diagram to assist you with installation.

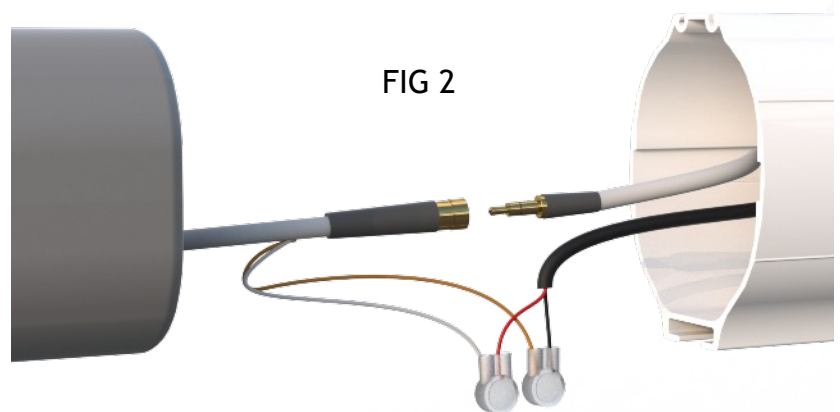
Pole With LED Lights



For Poles with no Safety edge fitted directly underneath (This will apply to Skirted Poles Also) Simply plug together the aux style lead found in the end of your pole and the end of your pole arm adapter. Shown Fig 1

Plain Pole with LED Lights and Safety edge

For Poles that have a safety edge fitted directly underneath the pole you will need to connect the safety edge to the excess cores on the light cable. If the excess cores have been wired from factory then the colours of the two cores will be orange and White as shown in Fig 2. Suitable water resistant connectors should be used, shown is an example of gel crimps being used.



Pole with Skirts and Safety edge



For Skirted Poles with a Safety edge You will need to Fix the Steel cable loop onto the barrier using the Provided M4 Fixings as shown in Fig 3. The safety edge cable can then be routed in to the barrier up in to the control panel. Connect the safety edge into the Feig Panel in Terminals 43 and 44 in the Yellow Terminal blocks. Refer to the Board connections Page

Step 6;

Now your pole is fitted and barrier level the tip support can be bolted down using the m12 fixings supplied (fig 11) and a suitable 12mm sds these can then be tightened using a 19mm spanner or socket (fig 12) and levelled to suit. The height can be adjusted to suit the barrier pole we would advise using a spirit level on the pole and raising the tip support to the under side of the pole before fixing in place. The m6 x 20mm button head bolts can then be drilled, tapped and fixed into place with the provided washers. (Fig 13) Final step is to trim the top of the m12 anchor bolts if required and fit the m12 caps from your fixings box for aesthetic purposes.

Fig 11



Fig 12

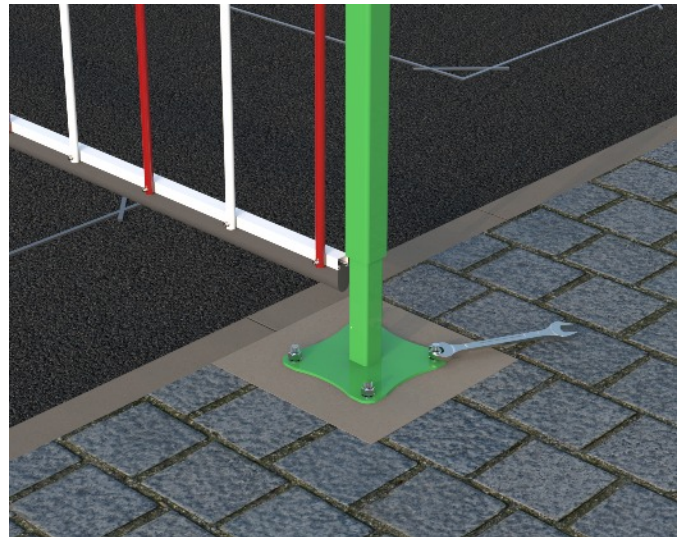


Fig 13

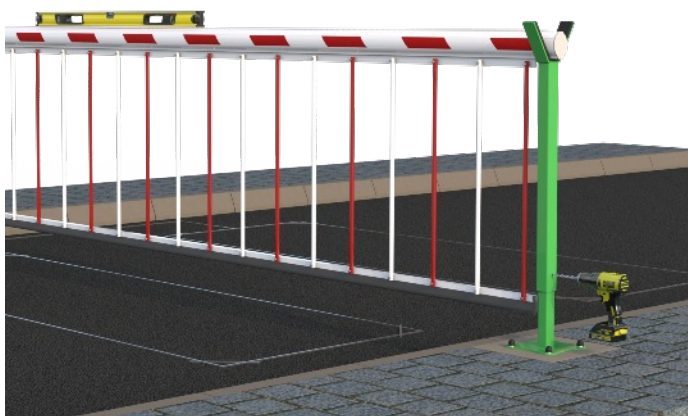
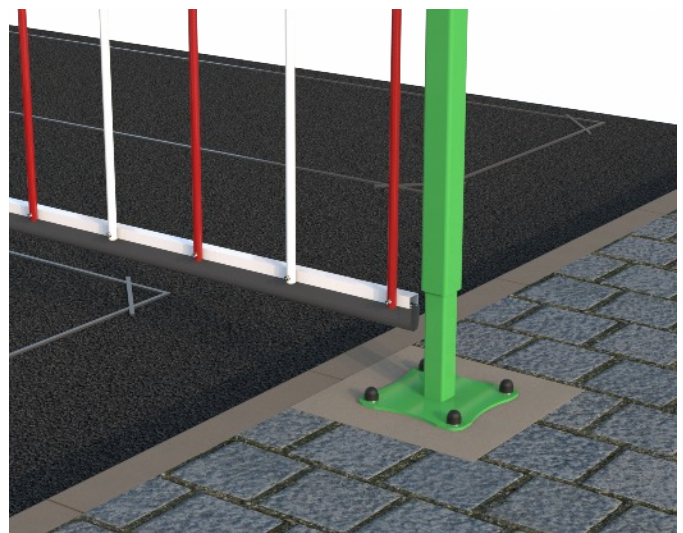


Figure 14



Connecting Up



Now that your barrier is fully installed you will be ready to connect your mains and access cables as well as your loops if required details of these connections are specified over the next few pages along with your positioning and programming guide.

The mains would be the first to connect using a 230v single phase supply at 16 amps this can be easily wired into our rotary isolator (1).

The access controls can be wired directly into the feig controller into the black block which is your common, open close and stop terminals (2).

The loops can be wired direct into the loop card and this added to the feig controller if required (3)

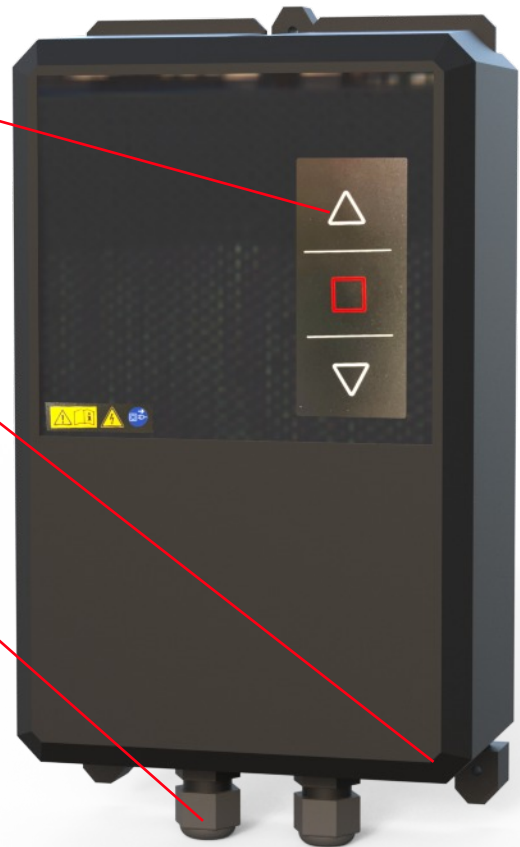
- 1
- 2
- 3



Operation and menu access buttons

Cover removal clips

Cable access glands



Terminal rail

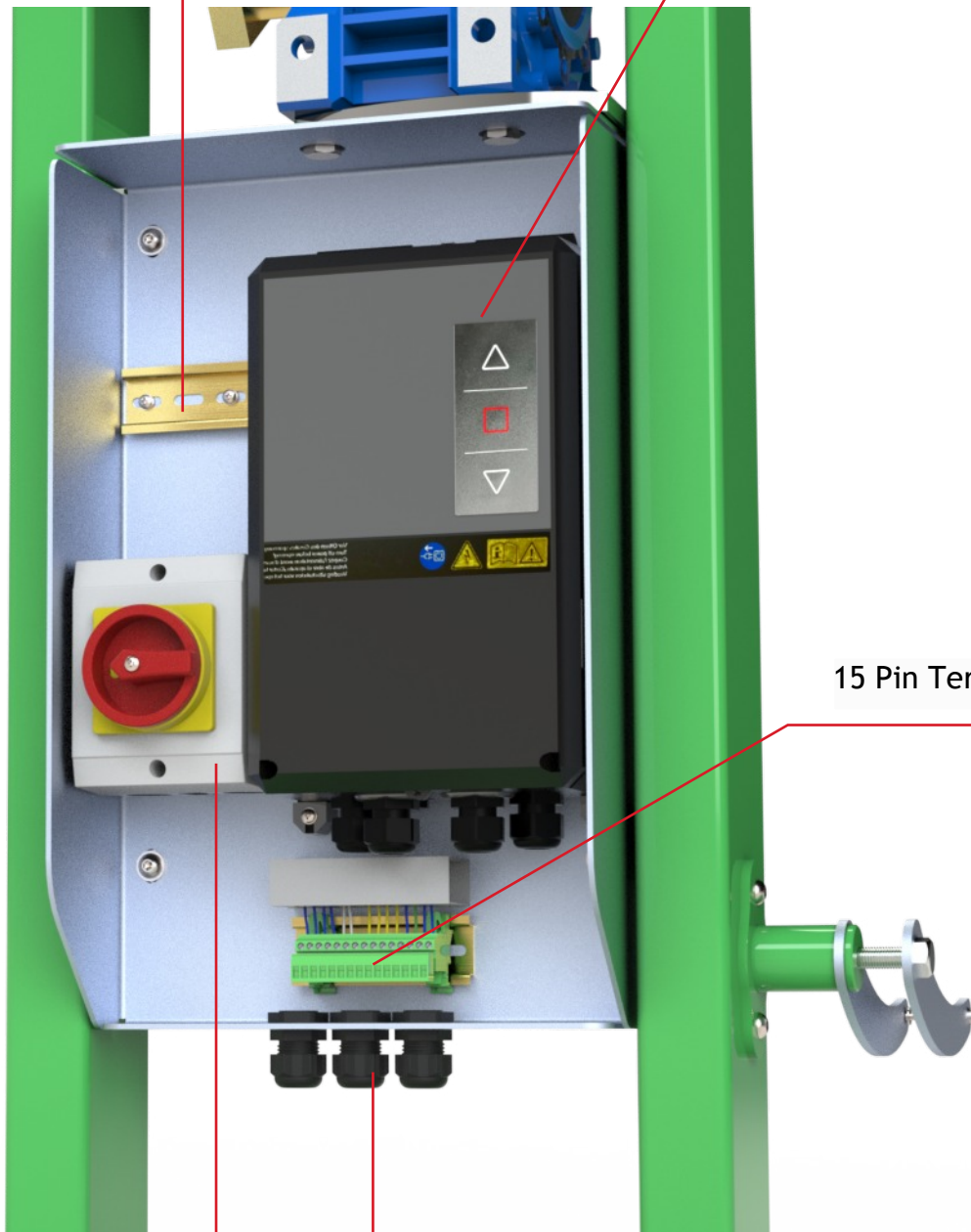
Traffic light relay

230v accessory supply

Above shows a typical barrier control panel layout which identifies the major components

Din Rail For Accessories

Feig Control Panel

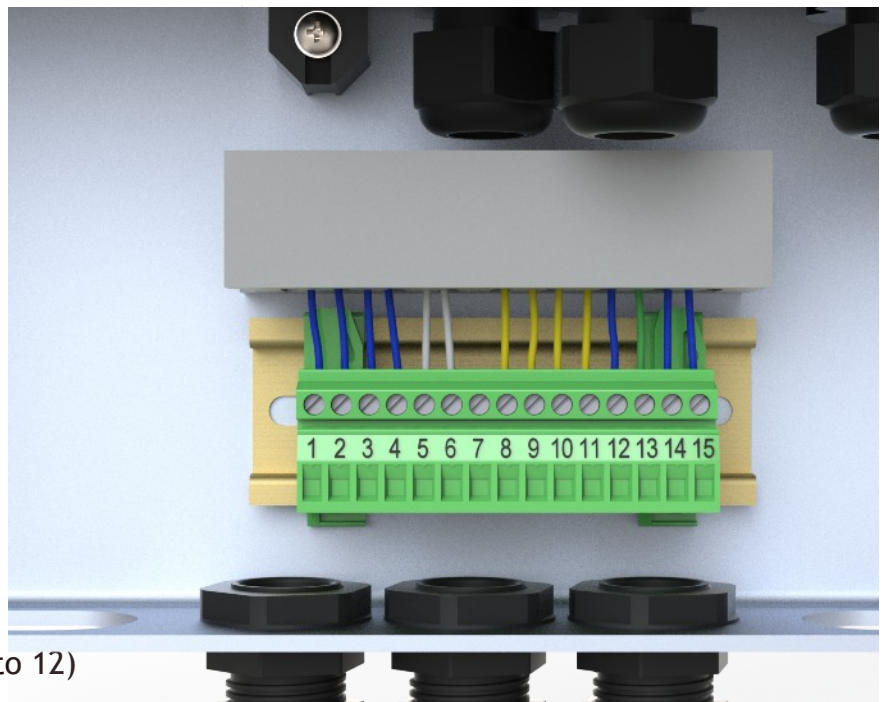


15 Pin Terminal Rail

20 Amp Rotary Isolator

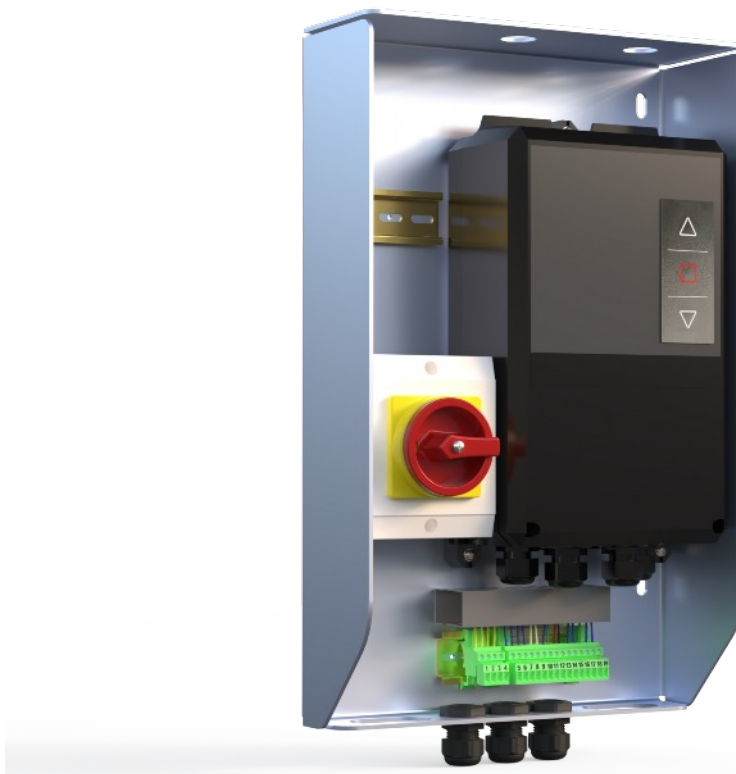
Cable Access Glands

- A. Loop Channel 1
- A. Loop Channel 1
- B. Loop Channel 2
- B. Loop Channel 2
- 1. Common 24v +
- 2. Stop N/C
- 3. Raise N/O
- 4. Lower N/O
- 5 Safety Edge 8k2
- 6. Safety Edge 8k2
- 7. External 24v +
- 8. External 24v -
- 9. Green Led / Traffic Light
- 10. Red Led / Traffic Light
- 11. Maglock 24v + (Negative to 12)
- 12. 24v + (photocells only)
- 13. 24v - (Photocells only)
- 14. Photocell Common 24v +
- 15. Photocell Contact 24v -



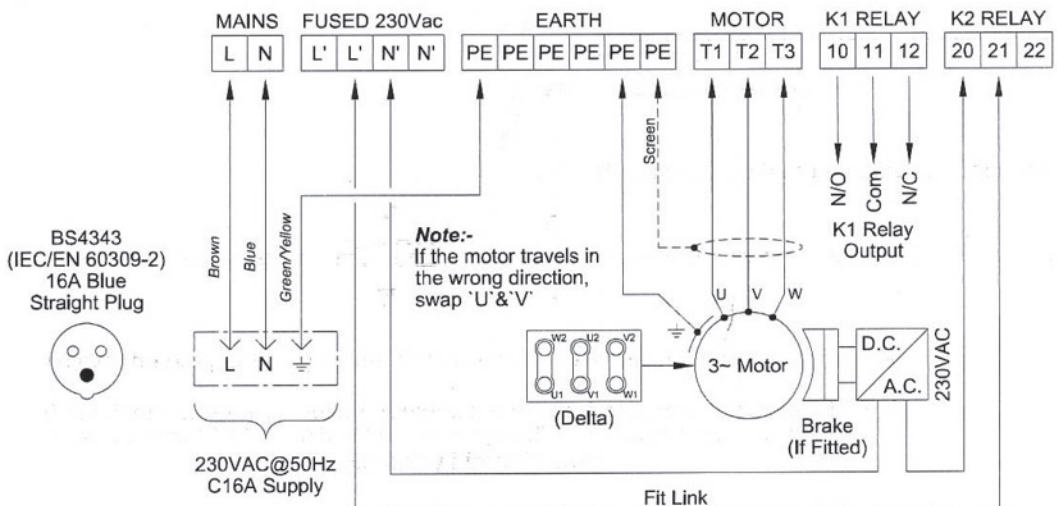
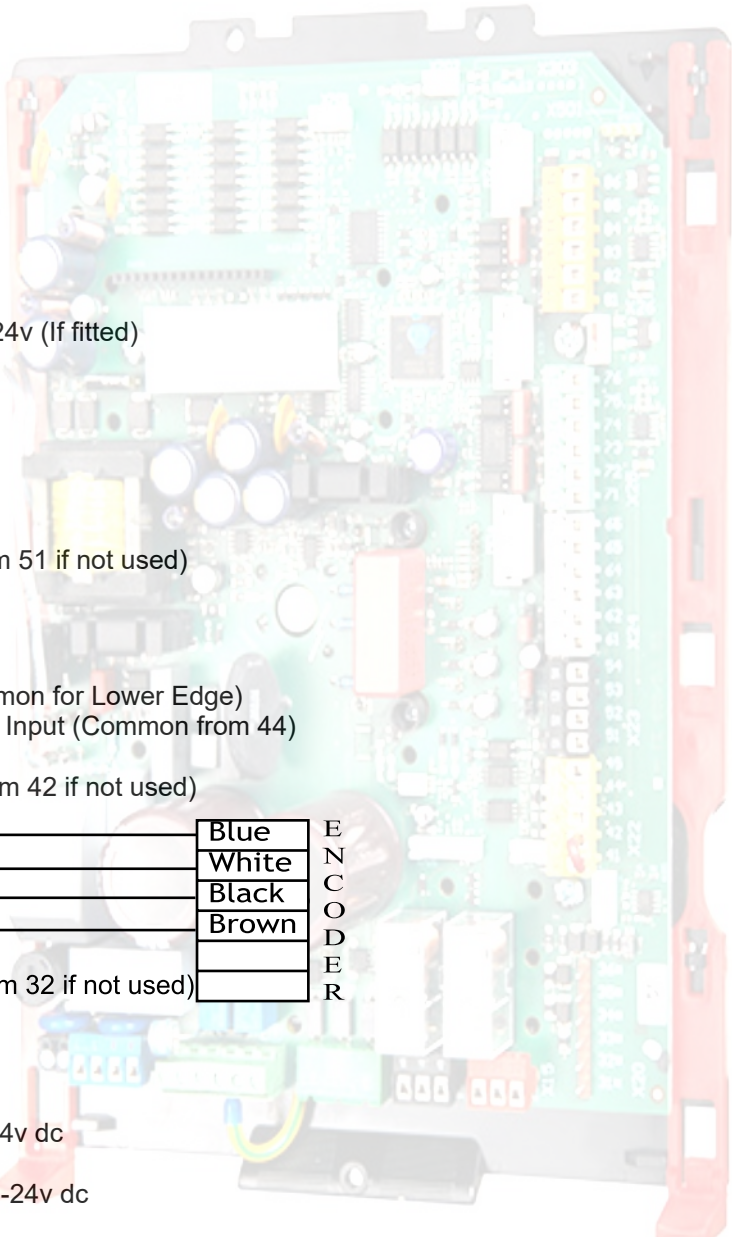
Safety and Auto loop bases

We now use the feig plug in loop cards for convenience of the engineer. If ordered with the product this will arrive with tails pre wired into the green terminal strip.



- 86 Common +24v dc
- 85 Open Dead Man
- 84
- 83 Common +24v dc
- 82 Close Dead Man
- 81
- 76 Common
- 75 Photocell
- 74 Ground -24v dc
- 73 Common +24v dc
- 72
- 71 Ground -24v dc
- 66 Beacon sounder +24v (If fitted)
- 65
- 64
- 63 Ground -24v dc
- 62 Common +24v dc
- 61
- 54 Lower Input
- 53 Stop Input (link from 51 if not used)
- 52 Raise input
- 51 Common +24v
- 45
- 44 Ground -24v (Common for Lower Edge)
- 43 Lower Safety Edge Input (Common from 44)
- 42 Common +24v dc
- 41 Stop Input (Link from 42 if not used)
- 36 Ground
- 35 Channel B
- 34 Channel A
- 33 +12v
- 32 Common +24v dc
- 31 Stop input (Link from 32 if not used)
- 22
- 21
- 20
- 12 Red Traffic Light -24v dc
- 11 -24v dc Link
- 10 Green Traffic Light -24v dc

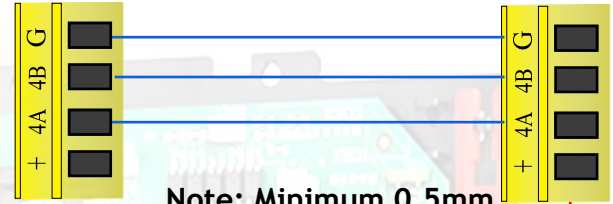
36	Ground	Blue	ENCODER
35	Channel B	White	
34	Channel A	Black	
33	+12v	Brown	
32	Common +24v dc		
31	Stop input (Link from 32 if not used)		



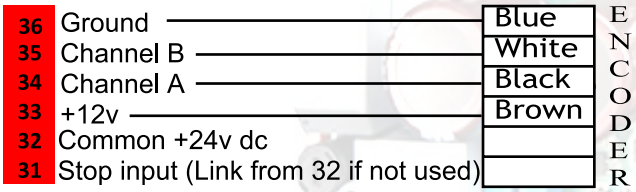
Master

Slave

- 86 Common +24v dc
- 85 Open Dead Man
- 84
- 83 Common +24v dc
- 82 Close Dead Man
- 81
- 76 Common
- 75 Photocell
- 74 Ground -24v dc
- 73 Common +24v dc
- 72 Slave Radar Contact If Fitted
- 71 Ground -24v dc (8K2 resistor between 71 and 65)
- 66 Beacon Sounder (common from 71)
- 65 Open Edge 8k2 Input (Resistor from 71)
- 64
- 63 Ground -24v dc
- 62 Common +24v dc
- 61
- 54 Lower Input
- 53 Stop Input (link from 51 if not used)
- 52 Raise input
- 51 Common +24v
- 45
- 44 Ground -24v (Common for Lower Edge)
- 43 Lower Safety Edge Input (Common from 44)
- 42 Common +24v dc
- 41 Stop Input (Link from 42 if not used)
- 36 Ground
- 35 Channel B
- 34 Channel A
- 33 +12v
- 32 Common +24v dc
- 31 Stop input (Link from 32 if not used)
- 22
- 21
- 20
- 12 Red Traffic Light +24v dc
- 11 +24v dc Link
- 10 Green Traffic Light +24v dc

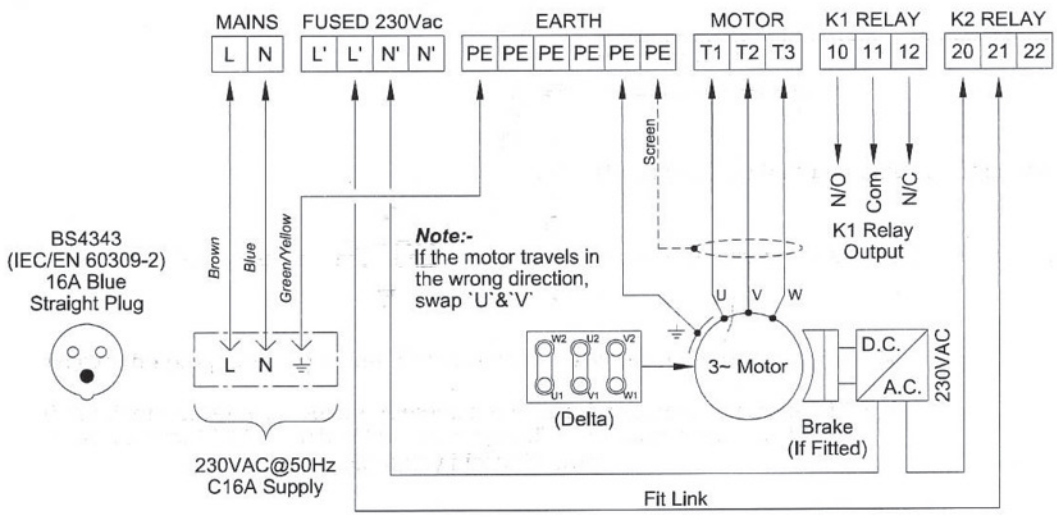
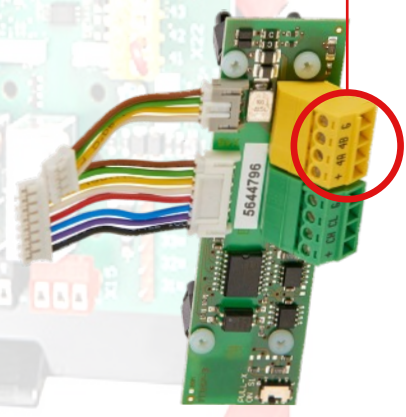


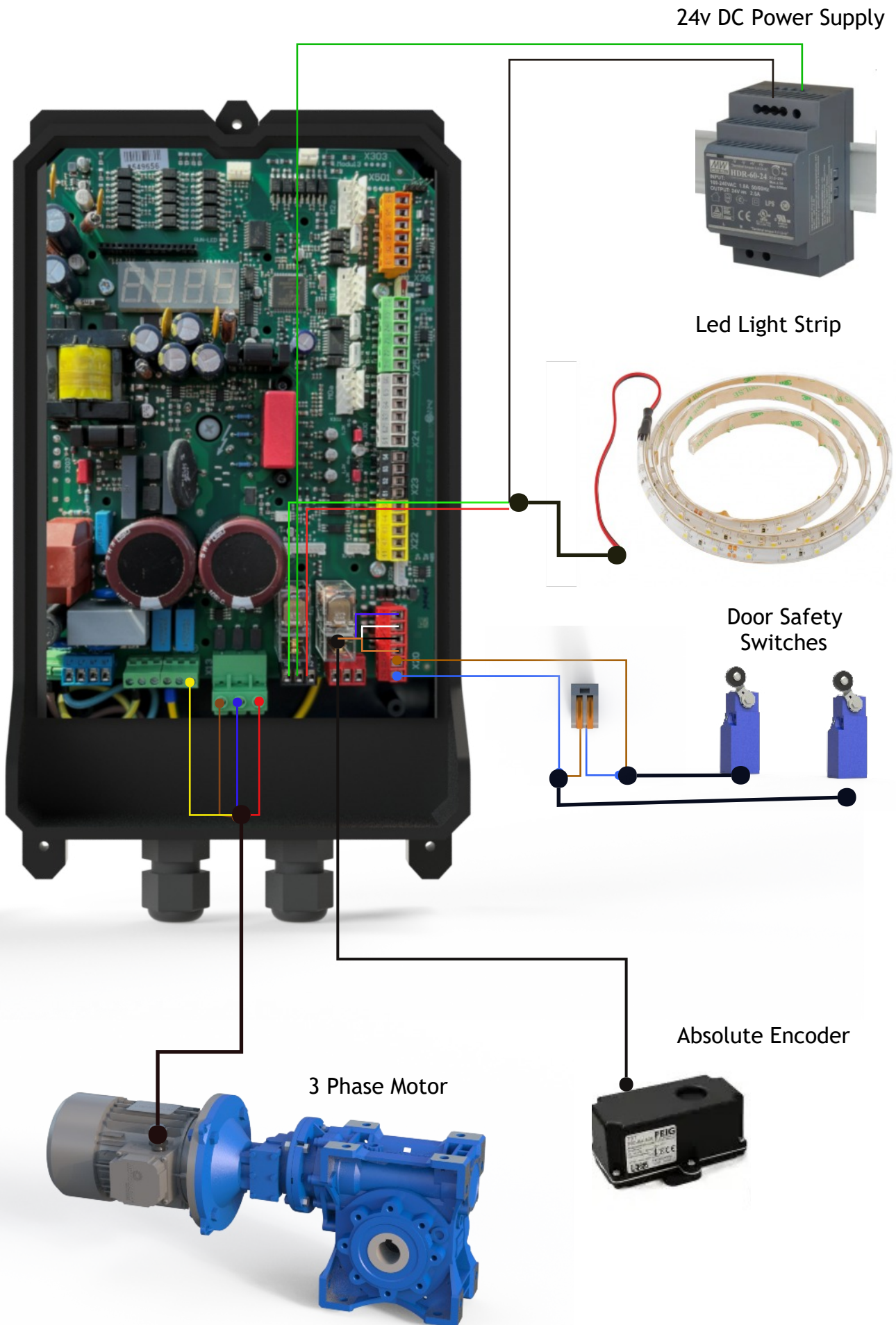
Note; Minimum 0.5mm Shielded cable to be used for this connection. Shielding connected to earths



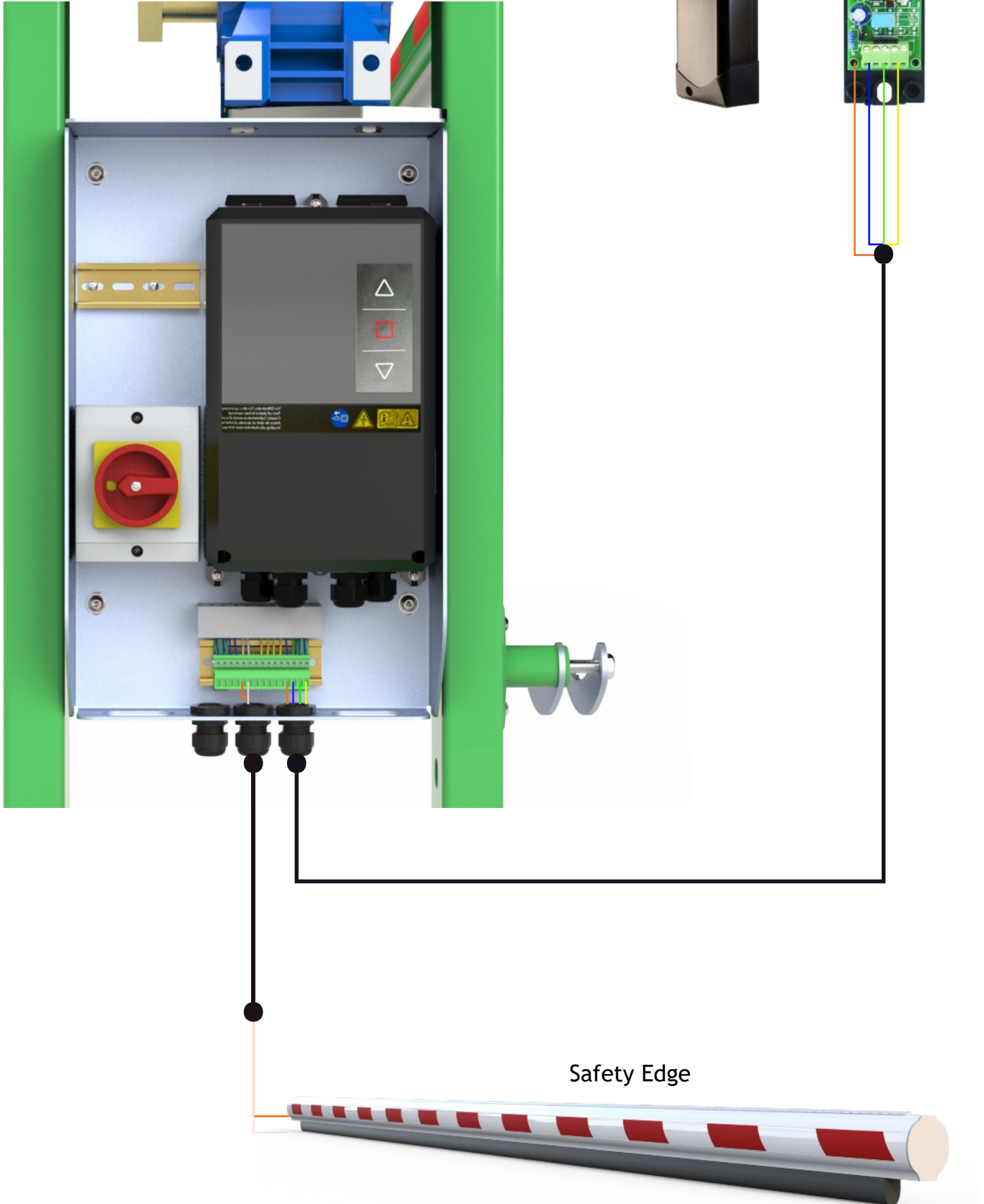
Master 2 core From relay 20 and 21

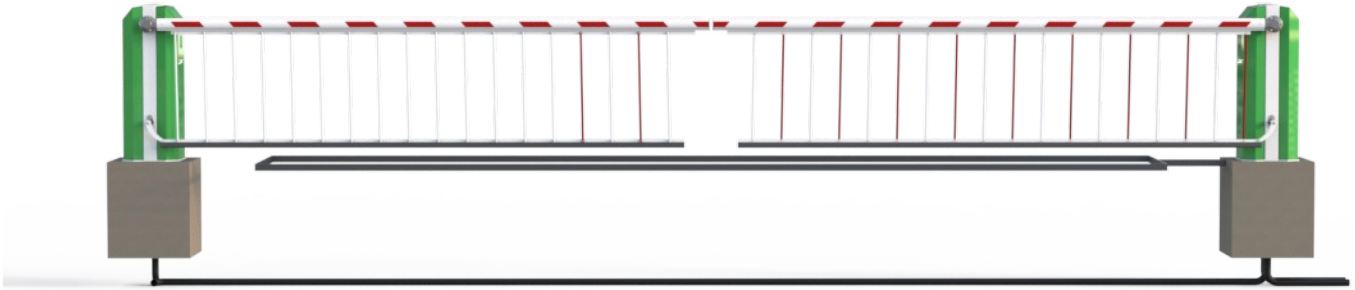
Slave Connect To terminals 41 And 42



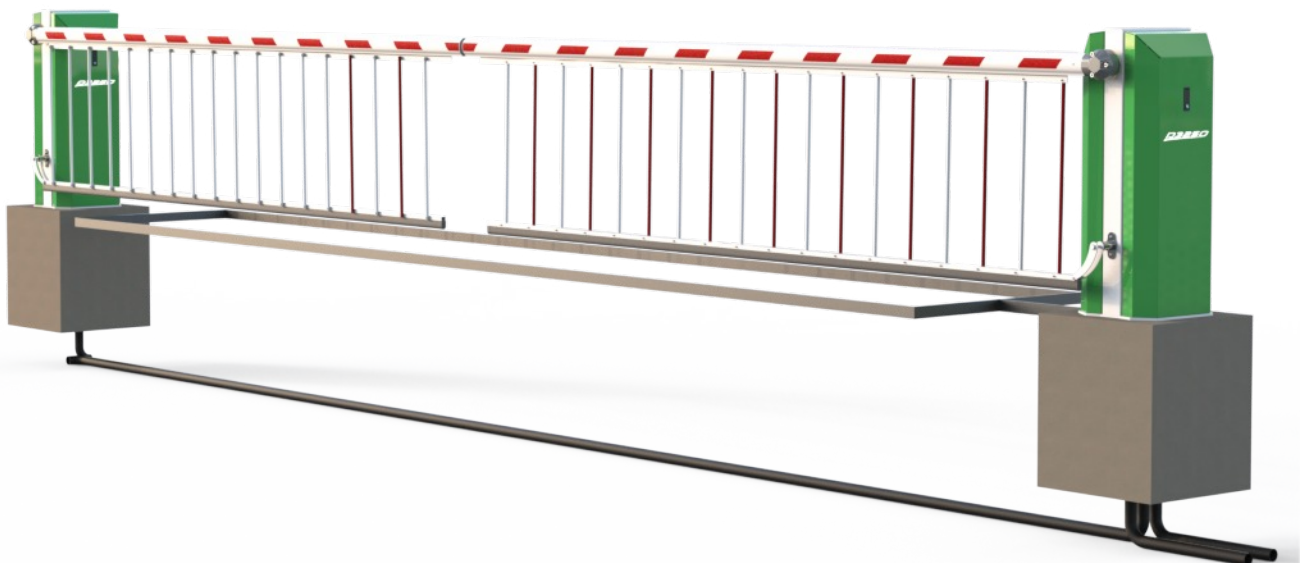


FT25B Photocell





Shown above and below are typical installations of a master / slave setup of our D3250 barriers. The connections between the two boards can be found in the previous pages. We would always recommend a minimum of 0.5mm screened cable to connect the boards together with the screening connected to the earths in the board to eliminate the chance of any interference. We would also recommend using separate ducts for mains and data cables to again reduce the risk of any interference on the board data connectivity. On our Master / Slave setup all signals and safeties such as loops, open signals, photocell contacts etc will be wired in to the master barrier. This will then relay the signals through to the slave barrier in real time. Both barriers will however need the mains supply connecting to them independently.



The D3250 barrier will arrive pre set to a point with all safety devices tested. The barrier is set-up and tested in our workshop prior to delivery without the pole being fitted. The limits therefore may need adjusting to suit your site or pole when fitted. Details on how to adjust these limits can be found in the previous pages. Please note: small adjustments shouldn't affect your slow positions dramatically, however should you wish to re-teach the slow downs etc, these details can be found over the next two pages. Should you be happy with the speeds and slow positions please follow the next two points.



At this point we would suggest allowing the barrier to fully close and make sure you are happy with run speeds and slow down positions.

Should you need to alter any of these settings, details can be found on the following pages on our walk through guide.

Initial Parameters used should you have master slave set-up to incorporate a radar or safety device to both sides these allow the slave barrier to transfer the signal back to the master via input 4 Terminal 72 so that both barriers react to the safety signal

Master			Slave			
Photocell Close	P.504	0505		P.504	0501	
	P.54B	2				
	P.54C	4				
Photocell Close	P.505	0501		P.505	0505	
	P.55B	1				
	P.55C	5				

Step 1,

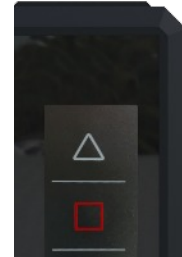
If you are happy with the barrier positions please test all safeties as normal, i.e. safety edges and photocells. If The barrier positions need resetting please follow the following few steps to re calibrate the encoders.

Step 2,

Should we need to reset the positions on the barrier please follow these steps.

You will need to access the parameters menu. This can be done by pressing and holding the stop and up arrows together. See figure 1

Figure 1

**Step 3,**

Navigate through the menu to parameter 999 (figure 2) using the up arrows. (Note holding the down arrow and pressing the up will move through parameters in blocks of ten for ease)

Figure 2

**Step 4,**

Once at P999 press the stop button; this will enter the parameter allowing you to change the value. Please set this to number 3 using the up arrows and confirm by holding the stop again for 2 seconds. Figure 3) to exit the parameter just press the stop key.

Figure 3

**Step 5,**

Now navigate through the menu to parameter 210 and set this to 5, this will reset the encoder allowing you to re calibrate the gate. Please follow previous steps until you are happy with the positions and safeties.

Note This setup is the same for a single barrier and master and slave pair. The buttons will only work the barrier to which they are installed. To test both barriers on a bi parting set-up, (Master and Slave) please use the open and close inputs on the board.

When you have the Barrier powered and ready to run please follow the next few steps to initially set up your encoder run positions. This will only need setting once.

Figure 4

Step 6;

Once reset, provided there are no faults, the board will display the message Cali, this is asking you to calibrate the encoder. Figure 4



Step 7;

When ready press the stop button briefly. The board will now display The EI-EC asking you to sync to lower position. Note the dots between the letters will be flashing.

Figure 5

Step 8;

Simply hold the down arrow to lower the barrier to its desired position, don't worry if you let go early, simply press the down to jog the gate to position. Once at your desired lower position press and hold the stop until the dots stop flashing. This will record the close position and then revert to the open sync, Figure 5



Step 9;

Now using the up arrow move the barrier to its desired raise position. Again, once happy, press and hold the stop button until the dots stop flashing to store the open position.



Step 10;

The barrier is now set and ready to operate, before testing safeties we would advise at this point to give the barrier an open and close operation to ensure the positions are correct and you can see the slow downs and ramps operating correctly.



Within the panel's display you are able to set the speeds of the drive to enable you to fine tune the barrier as per site requirements.

Select parameter code P999, Press 3 to unlock the menu to gain access to the below drive settings.

<i>Motor Code</i>	<i>Operation</i>	<i>Frequency</i>
P310	Opening Speed	Hz
P320	Opening Slow Speed	Hz
P322	Opening Ramp	Hz per second
P350	Close Speed	Hz
P360	Close Slow Speed	Hz
P362	Closing Ramp	Hz per second
P312	Open Acceleration	Hz per second
P352	Close Acceleration	Hz per second

Should you encounter any errors or make a mistake whilst programming, you can enter the full programming menu. Go to parameter 990 and set to number 2 which will reset the panel to our initial programme as factory set.

Note: when a safety edge is activated the drive will automatically back off in it's quickest possible time. You can also use the slow speed setting to alter your force test results if needed.

To set the timers on the feig board: follow the instructions to access the full parameters, 999 set to 3. The timers can then be adjusted as follows to suit sites requirements. Please note with timers and parameters setting them to the 0 position will turn the timer off.

Parameter	Description	Timers
P010	No Passage Timer	30
P020	Open Delay Timer	0
P025	Close Delay Timer	0
P712	Traffic Light Delay	0

Customisable parameters. Below is a list of parameters and functions that are offered with the control board. Please note the feig controller does not have a built in time clock. These can be supplied on request and programmed to suit site requirements.

Parameter	Description	Values
P000	Cycle Counter	Full Gate Cycle
P005	Maintenance Counter	Counter Set Between Service Periods
P920	Error Log	Last 8 Errors
P925	Software Version	Current Software Version
P985	Language	0 = English
P232	Open Slow Down	In Increments Of Travel
P222	Close Slow Down	In Increments Of Travel
P582	Normally Closed Limits	0 = On 1 = Off
P487	Safety Close	0 = Off 2 = On
P501	2 Step Logic	0204

Code	Description	Cause/ Rectification
Stop	Stop Movement	Membrane pressed/ awaiting command
EC	Close Position	Product in close position
EO	Open Position	Product in open position
Cali	Calibration	Awaiting calibration of positions
EIEC	Calibrating close	Close position calibration
EIEO	Calibrating Open	Open position calibration
'HD'	Deadman Operation	Safety fault or Deadman setting
Parameter	Description	Option
P010	No Pass Timer	0=off any other value=time to close
P020	Open Delay	Open delay set in milliseconds
P025	Close Delay	Close delay set in seconds
P100	Motor Fequency	Set in Hz
P101	Motor Current	Ampeage for motor
P102	Motor Power Factor	Set as a %, Motor cos
P103	Motor Voltage	Nominal Voltage
P140	Open motor boost	Percentage Boost during slow open 0-30%
P145	Close motor boost	Percentage Boost during slow close 0-30%
P202	Encoder resolution	Increasing halves increments
P210	Calibration Modes	Set to 5 to re-calibrate
P221	Fine adjustment close	Encoder only
P231	Fine adjustment open	Encoder Only
P310	Open speed	Set in Hz
P350	Close speed	Set in Hz
P920	Fault Log	Last recorded Faults

With the addition of the encoder operation the barrier now incorporates force detection. This is pre set in the programme however may need some adjustment whilst onsite depending on pole size or wind loading conditions etc.

The force detection works by stalling the motor in the lowering phase of the barrier and having this stall reacted to as a photocell. Our standard set-up has been created in our factory using a 4.5m boom which detects and reacts at 289 Nm of force and backs off in 0.45 of a second.

P.480 is the main parameter for enabling and disabling your force detection. Pre set to 2 the detection works by reading an alteration in the encoders operation. Setting this parameter to 0 will disable the force detection completely.

P.148 is the main parameters used for the force detection. This allows control of a voltage reduction during the closing phase of the barrier. This will be pre set to 60% of the full voltage; the higher this parameter is set, the more force will be behind the pole during lowering. The lower the parameter, the less force.

(Please note setting this parameter too low will cause an inertia effect and cause the boom to not run smoothly)

P.451 Set with a range of 0 to 100% This is the threshold incase of an obstacle detection. The higher the percentage set, the later the obstacle will be detected. This is pre-set to 42 as standard.

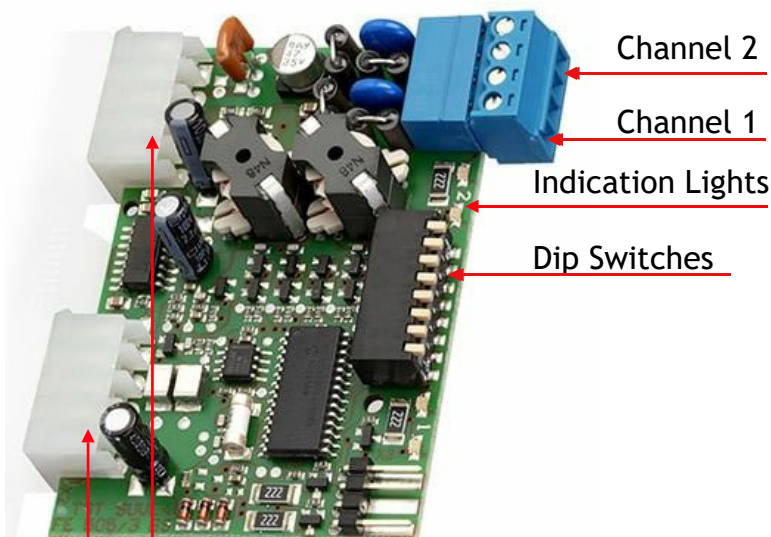
P.452 Also set with a range of 0 to 100%, this sets the dynamics incase of obstacle detection. This parameter can be used to smooth out disturbances at the beginning of travel, The lower the percentage on this parameter the later the obstacle is detected, This is pre-set to 60 as standard.

P.453 Set in increments between 1 and 250 This is the tolerance band for the slip in position of the encoder. This is pre set to 1 increment however may need to be increased for larger poles.

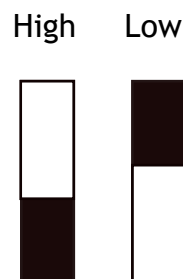


The loop board can be added to your Feig controller as per the diagram. These simply push in for ease, and allow easy control for single or dual channel.

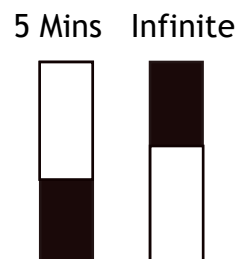
L.E.D Indications
 Green fast flash - Detector Tuning
 Green Solid Light - Detector is ready
 Green and Red on - Loop detecting
 Red Solid Light - Loop Fault



Frequency
 Channel 1 switch 4
 Channel 2 switch 8



Holding time
 Channel 1 switch 3
 Channel 2 switch 7

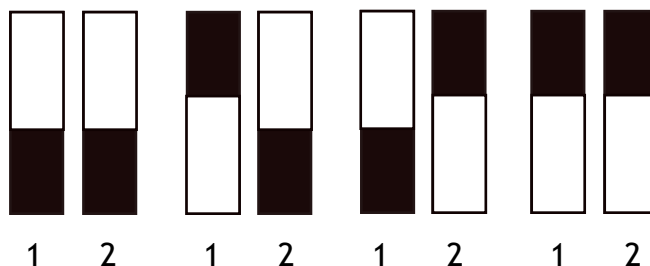


Dip switches 1 and 2 for sensitivity loop 1
 Switches 5 and 6 loop 2

Max



On



The loop card when used must be activated. This is done by changing up to three parameters on the feig controller depending on the application and functionality of the loops to be installed.

- P.802 - 0302 This activates the loop card.
- P.660 Channel 1 -
- P.670 Channel 2 -
- 23 This activates the safety function of the loop card.
- 22 This activates the free exit (open signal) from the loop card.
- 20 Turns the parameter off

If master slave or double leaf the 660 and 670 parameter will need changing on both panels.



Output Configuration,

The 2 x relays on the feig controller can be adjusted to control a number of options. These can be found in the list below.

For ease: Relay 1 = P701. Relay 2 = P702

The function of the output relay can be specified using this profile. All parameters needed for the function of the output are changed in one step.

- 0000: Output deactivated
- 0001: Continuously turned on
- 0101: Door is Open

The message depends on the logical status of the door

- 0103: Door is Open

The message depends on the position of the door

- 0201: Door is Closed

The message depends on the logical status of the door

- 0203: Door is Closed

The message depends on the position of the door

- 0401: There is no error
- 0501: Courtyard light function, switched ON during opening and closing with 10 s switch off delay after closing.

- 0601: Passing on detector channel 1
- 0602: Passing on detector channel 2
- 0605: Synchronous control OPEN, signal duration 0.5 seconds.
The output is active during opening, in End position OPEN and during locking in end open position.

- 0606: Synchronous control CLOSE, signal duration 0.5 seconds.
The output is active during Closing, in End position Close and during locking in end position close.

- 0607: Synchronous control STOP, signal duration 0.5 seconds.
The output is active when the door is not moving, no end position is approached and no locking in any end position is active.

- 0612: Passing on leaving detector 1
- 0613: Passing on leaving detector 2
- 0630: Forwarding Brake
- 0634: Forwarding, of an low Battery from the WiCab mobile Unit
- 0659: F.363: forwarding disturbance of the internal safety edge.
- 0660: Forwarding: maximum number of trips of the safety edges has been exceeded.

- 0665: Forwarding detector channel 3
- 0666: Forwarding detector channel 4
- 0701: Flashing during opening and closing
- 0703: Switched on during Opening and Closing
- 0801: Active during opening and closing and during active pre-warning / clearance time.

- 1001: Locking second door
- 1002: Locking second door, 1 s switch off delay

- 1101: Magnet voltage in end position CLOSE



The N.C. contact of the relay has to be used

- 1102: Magnet voltage during Closing and in end position CLOSE

- 1201: Green traffic light on inside of door
- 1210: Green traffic light on outside of door
- 1220: Red traffic light on inside of door 1
- 1221: Flashing red traffic light on inside of door 1
- 1222: Red traffic light on inside of door 2
- 1223: Flashing red traffic light on inside of door 2
- 1224: Red traffic light on inside of door
- 1232: Red traffic light on inside
- 1233: Red traffic light on inside, inverted
- 1250: Red traffic light on outside of door 1, flashing during clearance time
- 1251: Flashing red traffic light on outside of door 1
- 1252: Red traffic light on outside of door 2
- 1253: Flashing red traffic light on outside of door 2
- 1255: Red traffic light on outside of door
- 1263: Red traffic light on outside
- 1264: Red traffic light on outside, inverted
- 1295: Green traffic light, flashing during pre-warning / clearance time, ON in end position OPEN
- 1298: Direction dependent red traffic light. On for opening and closing movement. Off when CLOSED and when OPEN. Flashes during evacuation time
- 1601: Airlock OPEN
- 1701: Testing in end position close
- 1801: Counting +



The function is only possible with detectors 1 and 2. At first you have to activate the + loop and then the - loop.

- 1901: Counting -



The function is only possible with detectors 1 and 2. At first you have to activate the - loop and then the + loop.

- 2001: Warning light 1, always ON if door is not closed.
- 2101: Warning light 2, switched ON during closing
- 2201: Active green traffic light, ON in endposition OPEN until a close command is given or detector 2 gets active.
- 2301: Active green traffic light, ON in endposition OPEN until a close command is given or detector 1 gets active.
- 2501: Testing in endposition OPEN
- 2601: Emergency opening test
- 3201: Output function brake
- 3202: Output function brake (N.C., output turned)



The exact settings which this profile involves can be found in Appendix Output Profile.

Step 1;

First make sure the Mains supply is isolated and the barrier has no pole on. Then using the Manual winder, Wind the barrier into the half way position as shown in Fig 1, this will allow you access to the M16 Turnbuckle bolt that needs to be removed Shown in Fig 2.

Fig 1

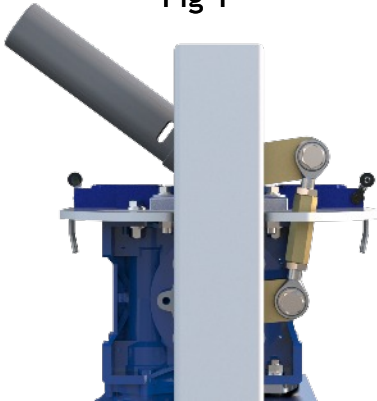


Fig 2



Step 2;

Now wind the Gearbox shaft round in the opposite direction as shown in Green in Fig 3. Now move the top shaft around to the opposite site and insert the M16 Turnbuckle bolt back into the top Lever as shown in Fig 4. Ensure Thread lock is used and the Bolt is tightened.

Fig 3

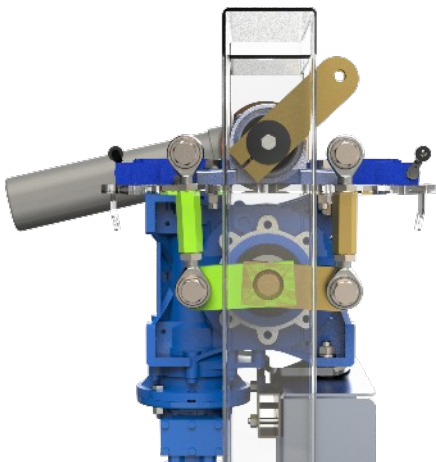
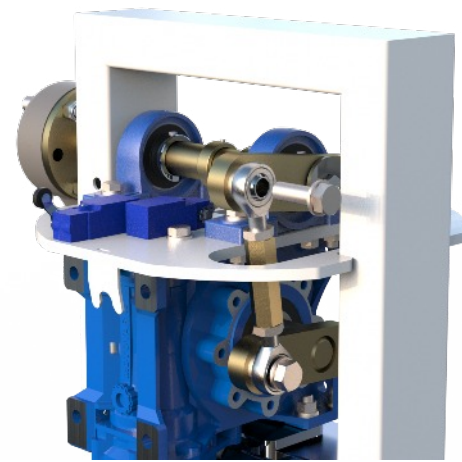


Fig 4



Step 3;

You will now see that the Pole arm adaptor is set at the wrong angle See Fig 5, The Green Pole arm adaptor indicates the correct angle. You will now need to remove the 3 x M12 pole arm adaptor bolts and locate the pole arm adaptor on to the next set of holes in the top shaft, This is 60 degrees difference. Fig 6

Fig 5

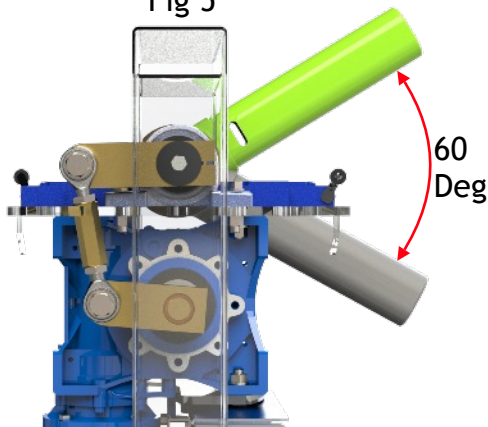
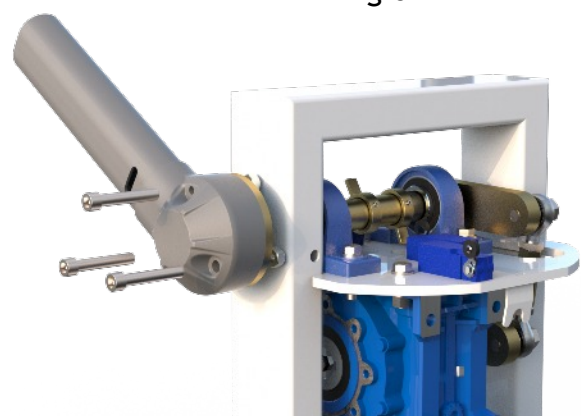


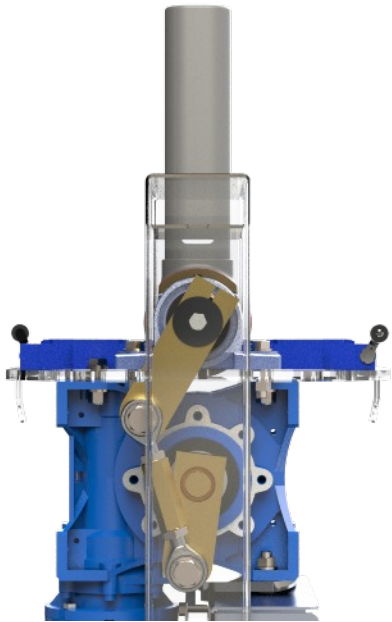
Fig 6



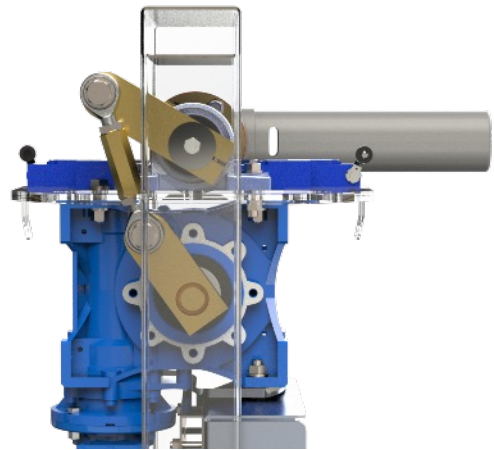
Step 4;

Now check you have the handing set correctly by winding the gearbox to the fully raised and lowered positions. Check using the below images that your barrier matches these images in each position.

Left Hand Raised



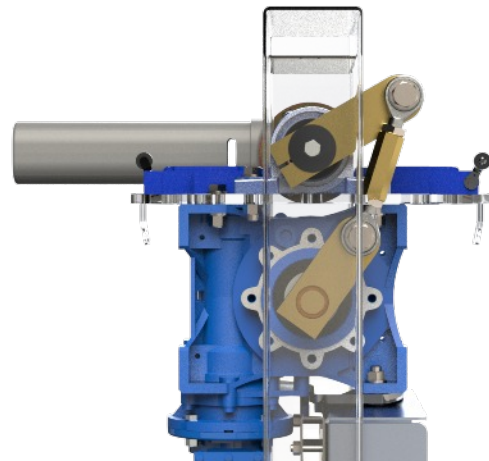
Left Hand Lowered



Right Hand Raised



Right Hand Lowered



Step 5;

Now you have the handing completed mechanically, you must now swap the motor direction - Please see below image. By swapping 2 of the phases the wiring can be found inside the Feig board. See below. Once this is complete please follow the calibration instructions in the set up guide.

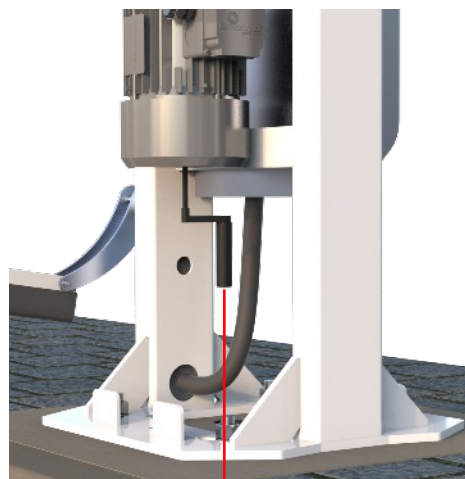


To reverse the motor swap any 2 of the phases

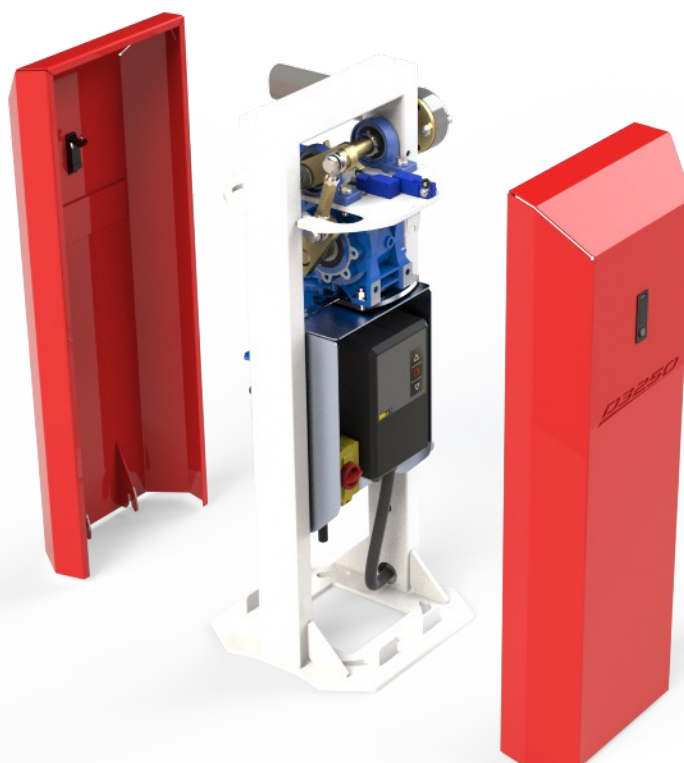
Please use the following instructions to operate the barrier manually, the following is assuming you have powered down the unit.

To Manually release the barrier please remove the cover using key supplied, then take the release handle (which will be handed over with the keys) and insert into the motor and rotate. Direction depends on Barrier handing. Once the barrier is wound to the desired position replace the release key and replace the cover and re-lock.

Note the cover has a safety switch on it that will not allow the barrier to operate if the cover is Not fully closed.



Manual Release Handle



MECHANICAL ERRORS	CAUSE	CORRECTION
Barrier arm keeps going up and down	Limit switch fault	check and reset limit switches
Barrier creaking when moving	Check bearings	Oil or grease bearings
Barrier motor not running	Loss of voltage	Check motor supply test 3 phases
Barrier not raising or lowering	Positioning / Motor issue	Call service team to diagnose fault
Barrier not raising or raising half way	Gearbox	Gears stripped due to overloading replace
Barrier raises slowly and lowers too quickly	Slow positions not defined correctly	Contact installer to re-commission
Barrier not running at all	Door has been left open or switch not pushed in	Close the door and issues a signal to open or close
Barrier raised will not lower	Key switch is left in open position	Turn key switch to auto
	Loop fault or loop detecting	Check if green light is on detector if so remove object that it is detecting or
ELECTRICAL ERRORS	CAUSE	CORRECTION
Blank screen on lcd but power to other devices in the control panel	On-board fuse blown or short	Unplug accessories / Replace fuse
	Lcd has developed an electrical fault or had power spike	Change control panel
Barrier does not run (stays open)	Check Controller for error code	Locate issue as appropriate to code
	Loop detector is faulting or sensing presence	Clear obstacle / reset the detector
	Check Photocells power	24vdc or 3.6v Batteries to replace
	Barrier staying up in raise position	Open signal latched from access controls
	Photo cells dirty (if fitted)	Clean photo cells make sure they are debris free
	Stop circuit broken	Check door switches/access controls
Mains on but no power	Isolator fuse	Check and meter fuse in isolator
Barrier not going up	Access control may be faulty	Raise and lower barrier from buttons on controller
	Door switches poor contact	Remove and re-fit doors

Code	Description	Fault / Rectification
F000	Traveled Past calibrated open	Check Speeds/ Encoder Slip / Re-calibrate
F005	Traveled Past Calibrated open	Check Speeds/ Encoder slip / Re-calibrate
F020	Run Time exceeded	Check P410/P415/P419
F030	Lag Error	Check Boost settings P.140 / P.145
F031	Moving wrong direction	Channel A/B reversed. Recalibrate p210
F211	E-Stop	Terminals 41/42
F212	E-Stop	Terminals 31/32
F325	Obstacle During Closing	Adjust force detection settings
F360	Closing edge activated	Edge detected terminals 43/44
F363	Interruption closing edge	Check for 8k input
F380	Open edge activated	Edge detected terminal 63/65
F383	Interruption open edge	Check for 8k input
F425	Overvoltage Supply	Incoming mains voltage too high
F426	Undervoltage Supply	Incoming mains voltage too low
F430	Heat sink temp out	Power stage too high
F515	Motor Overcurrent	Boost settings too high, P140/P145
F700	Position Unknown	Cali not set or recalibrate P210 to 5
F752	Loss of Comms with Encoder	Interface cable defective/No 12v supply
F766	Encoder Error	Re-calibrate P210-5
F76A	Encoder Magnetic Field	Re-fit magnet further into encoder
F7A2	Expansion Board error	Loss of coms master/slave
F930	External watchdog error	Moisture on board / Hardware error

Code	Description	Reason
E000	Open pressed Membrane	
E050	Stop pressed Membrane	
E090	Close pressed Membrane	
E101	Open input	Open activated
E102	Stop input	Stop activated
E103	Close input	Close activated
E104	Ped open Input	Ped activated
E105	Photocell input	Photocell activated
E106	Dead open input	Deadman open activated
E107	Dead close input	Deadman close activated
E108	Open limit input	Open limit activated
E109	Close limit input	Close limit activated
E110	Input 10	Open safety input loss of 8k
E201	Membrane stop pressed	
E211	E-stop	Terminals 41/42 open
E212	E-stop	Terminals 31/32 open
E360	Close edge input	Terminals 43/44 open
E363	Close edge resistance	Terminals 43/44 no 8k
E380	Open edge input	Terminals 63/65 open
E383	Open edge resistance	Terminals 63/65 no 8k
E501	Loop detector channel 1	Channel 1 active
E502	Loop detector channel 2	Channel 2 active

We certify that the system covered by this certificate has been commissioned satisfactorily.			
Site Name		Completion	
Site Reference		Engineers Installing	
Installation Commenced	/ /	Commissioning	
Equipment Fitted			
Handover Date			

Part 2. Existing Installation Items not covered under warranty/ This certificate:

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Part 3. Certificate Signing off

Installers Name		Signature	
On Behalf of		Date of Signing	
Address		Position	
Client Name		Signature	
On Behalf of		Date of Signing	
Site Address		Position	

Part 4. Onsite training for product usage

Trainers Name,	Date	Competency / Job Title	Signature
Attendees Name	Date	Signature to confirm understanding	



As stated at the beginning of this manual, we recommend a bi-annual service, but at a bare minimum, it is imperative that you get a service done once every 12 months. This is not a sales tactic in disguise, there is a very serious health and safety issue/risk associated with not complying with this. Also in order for your barrier to keep complying with the appropriate legislation. All machinery products must conform to BS EN 12453:2017+A1:2021 for the supply of powered machinery safety regulations.

Before carrying out any maintenance to the installation, disconnect the mains power supply.

A Maintenance Contract should be sought from a specialist company after a maximum of 5000 manoeuvres or 1 year from the install date.

Occasionally clean the photocell optical components and make sure they are free from dirt, water, rain, soil etc.. Batteries in photo cells may need to be changed on every service or sooner dependant on use. Barriers will not work properly without photo cell function..

If the power supply cable is damaged, it must be replaced by a suitably qualified person, in order to prevent any risk. This must conform to BS 7671:2018+A3:2024

When any operational malfunction is found, and not resolved, disconnect the mains power supply and request the assistance of a qualified technician (installer). When automation is out of order, activate the manual release to allow the opening and closing operations to be carried out manually.

Gearbox drive unit is “sealed” for life and requires no further lubrication.

Maintenance Check List;



- Door Locks Checked
- Bearings Greased
- Rod Eye Bearings Checked
- Safety Devices Checked
- Door Switches Checked
- Encoder Checked

-
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-



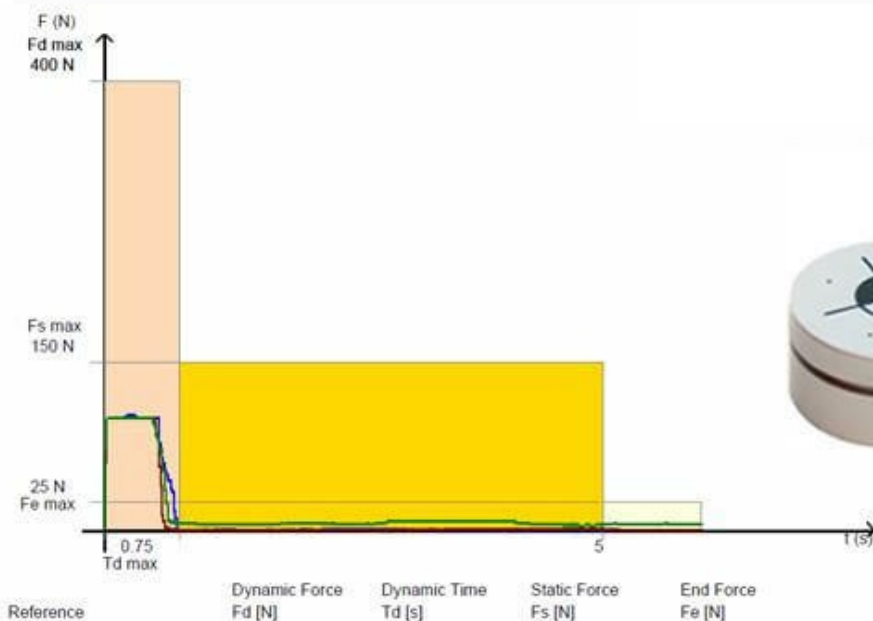
Your Barrier will conform to BS EN 12453:2017+A1:2021 the standard for powered machinery, and any additional amendments to this critical safety standard. We manufacture barriers and equip them with safety and other options, only to the extent specified by our customers. Therefore, the barriers, as delivered, may not represent a complete machine as defined by the regulations. As such, the addition of any after market safety devices by the client must conform to this standard as well as BS EN 12978:2003+A1:2009 the standard for sensitive safety devices. The three main points of covered in this standard are the installation, design and elimination of hazards and electrical control system integrity; also the Implementation of devices designed for safe contact (force limitation) such as resistive safety edges. The standard also covers Non Contact (presence detection that prevents hazardous contact) such as, and not limited to, photocells, light curtains, radar sensors and inductive loops.

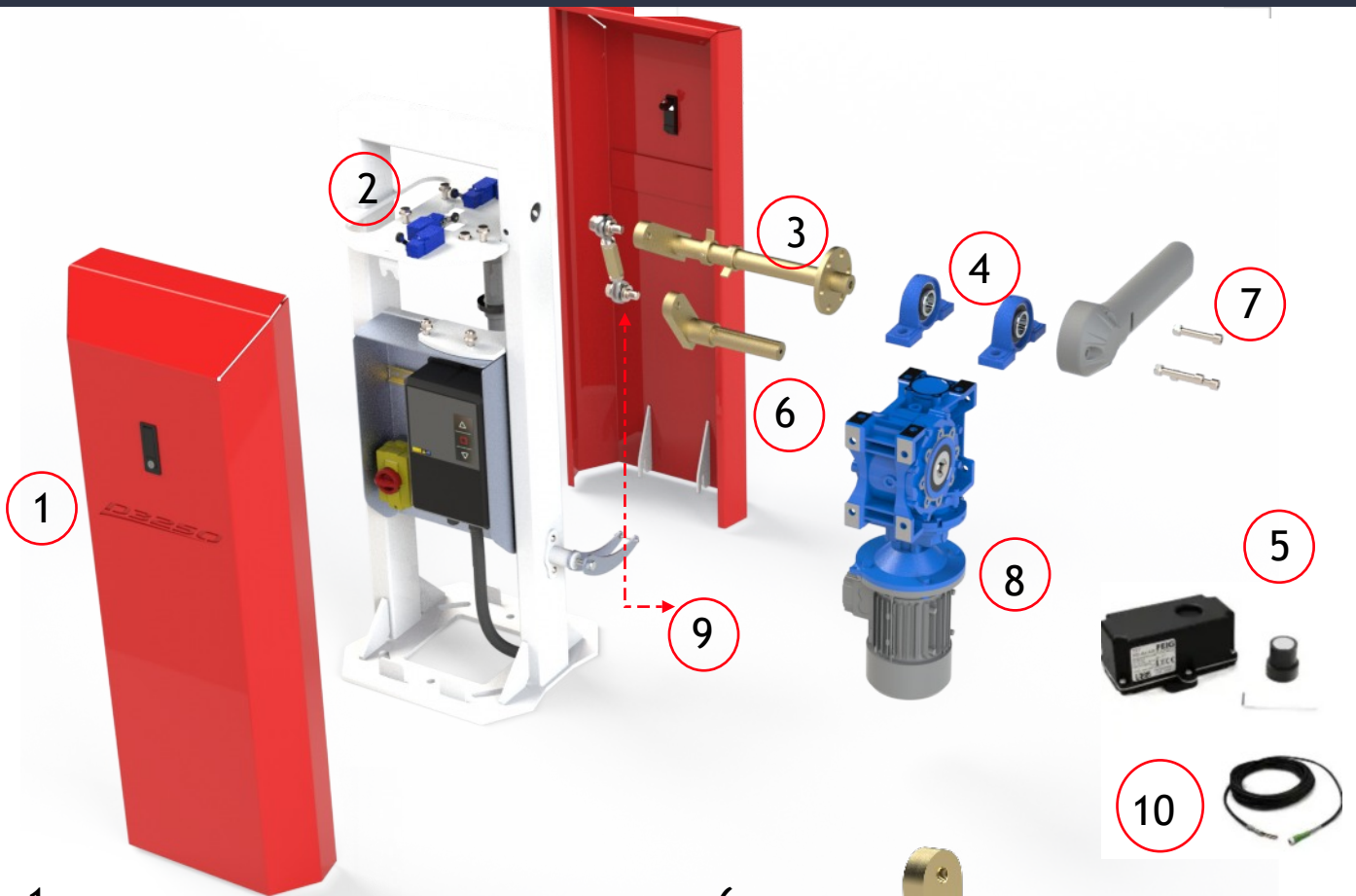
It is imperative that the installer carries out an on-site risk assessment prior to fitting or maintaining barriers, and a residual risk assessment once the installation is complete. These will highlight any remaining safety issues, and allow the installer to fit additional equipment or draft suitable protocols for operation of the equipment. Therefore the product must be installed and maintained by a competent, qualified and well trained company or individual.

As standards are ever improving the safety devices and systems in use may need to be upgraded from time to time. The standards will always refer to 'state of the art' safety devices being used in conjunction with the product. However the emphasis is always preferred on non contact devices with the back up of sensitive (force detecting products also).

To add additional safety products and accessories to an existing product the relevant paperwork and Declaration of Incorporation (or Certificate of Compliance as appropriate) must be updated and kept for the relevant standards to be adhered to.

All Electrical supplies to Barriers and machine products must be installed to the correct Standard i.e. the current edition of BS 7671:2018+A3:2024 and any alterations to this supply must be recorded and adhere to this standard. These can be recorded in the Electrical installation Certificate or the Periodic Inspection report.





1



Door Lock

2



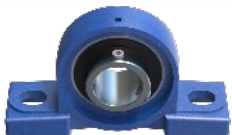
Limit Switch

3



Shaft Assembly

4



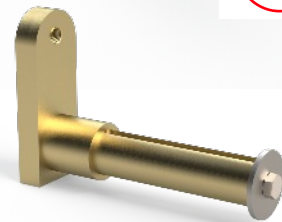
Top Shaft Bearing

5



TST - PD2 Encoder

6



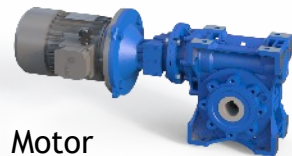
Motor Shaft

7



Pole Arm Adapter

8



Motor

9



L/H rod eye - Turnbuckle - R/H rod eye

10



Encoder Cable



This Manual must be completed in accordance with the guidelines below, at any point service/repair work is carried out on the product. This is to achieve two things;

1. To keep a history of the product for yourself and your supplier/manufacturer.
2. To keep an accurate log of any historical or recent modifications, and/or problems, to help an engineer in the event of any future work required on the product.
3. This page is continued on the next page if extra space is needed.

Date	Reason for visit/Action taken	Engineers Signature
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Ultimation Direct Ltd
Maltkiln Lane, Newark, Notts, NG24 1HN
Tel: 01636 550300
Email: enquiries@ultimationdirect.co.uk

Declaration of Conformity

In accordance with BS EN ISO/IEC 17050-1:2010

We: Ultimation Direct Ltd
Of: Trent Lane, Maltkiln lane, Newark, Notts NG24 1HN In

accordance with the following directives:-

- Supply of Machinery (Safety) Regulations 2008
- Electromagnetic Compatibility Regulations 2016
- The Radio Equipment Regulations 2017

Hereby declare that:

Equipment: Automated Traffic Barrier
Model no: D3250E

Are in conformity with the applicable requirements of the following documents:

- Supply of Machinery (Safety) Regulations 2008.
- BS EN 12453:2017+A1:2021 Industrial, commercial and garage doors and gates—Safety in use of power operated doors— Requirements.
- BS EN 12604:2017 Industrial, commercial and garage doors and gates—Mechanical aspects—Requirements and test methods.
- BS EN 13241:2003+A2:2016 Industrial, commercial and garage doors and gates - Product standard. Products without fire resistance or smoke control characteristics.
- BS-EN12978:2003 Industrial, commercial and garage doors and gates. Safety devices for power operated doors and gates. Requirements and test methods.
- BS EN 13856-2:2013 Safety of machinery. Pressure sensitive protective devices. General principles for the design and testing of pressure sensitive edges and pressure sensitive bars.

I hereby declare that the equipment named above has been designed to comply with the relevant sections of the above referenced specifications. The unit complies with all applicable Essential Requirements of the Regulations.

Signed:

Name: Matthew Mulholland
Position: Technical Director
Place: Newark
Date: March 2026



Specification

Maximum Boom Length: 7.0 metres
Power Requirement: 230v, Single Phase, 50Hz, 16 Amps
Drive Motor: 3 Phase motor & wormed gearbox
Opening/Closing time: 1.5 - 7.0 seconds
Duty Cycle: 100% continuous duty rating
Operation Time: 8 Seconds per metre (Variable)
Finish: Polyester Powder Coated
Dimensions: 420mm x 405mm x 1138mm

Access Controls: Push-button, Proximity cards, card readers, tokens, voice/video intercoms, keypads and remote fobs.

Motor/Gearbox

Electric Motor:

400v 50hz 3 phase
 4 pole
 IP55
 8mm End Cap
 B14 C face mounted
 Frame size 80
 Output power: 0.55kW
 Current @ 400v: 1.70A
 Rated speed: 885rpm
 Full-load power factor(cos): 0.72
 Full-load efficiency: 65%
 Locked rotor current is/in: 4.7
 Locked rotor torque Ms/Mn: 2.0
 Break down torque Ms/Mn: 2.1
 Net weight 9.2kg
 Driving end bearings: 62042RS/C3

Geared Motor Spec:

Type: Worm & Wheel
 Overall speed: 2 rpm
 Max rated torque: 1050nm
 Actual torque: 1000nm
 Gearbox efficiency: 40%
 Output size: 42mm
 Mounting position: V5
 Angular Backlash: 15' +/- 5' / 0.00436
 +/- 0.00145 (W110)
 Lubricated with: Shell Omala 1.7 litres (W110)

Accessories

Optional extras:

- ✍ Folding bottom skirt up to 6.0m
- ✍ Hi-Bar skirt up to 5.0m
- ✍ Articulated arm (low ceilings)
- ✍ Pogo tip support
- ✍ Boom lights
- ✍ Magnetic lock
- ✍ Lorry height stop/no entry signs
- ✍ Warning sounder/flashing Beacon
- ✍ Sensing safety edges

Made in the UK

